

Show *all* of your work and *explain* your answers fully. There is a total of 95 possible points. If you use a calculator on a problem be sure to write down both the input to, and output from, the calculator.

1. Determine if the set S below is linearly independent or linearly dependent. (15 points)

$$S = \left\{ \begin{bmatrix} 2 \\ 1 \\ 3 \\ -1 \\ 2 \end{bmatrix}, \begin{bmatrix} 4 \\ -2 \\ 1 \\ 3 \\ 2 \end{bmatrix}, \begin{bmatrix} 10 \\ -7 \\ 0 \\ 10 \\ 4 \end{bmatrix} \right\}$$

Solution: Theorem LIVRN suggests we analyze a matrix whose columns are the vectors from the set,

$$A = \begin{bmatrix} 2 & 4 & 10 \\ 1 & -2 & -7 \\ 3 & 1 & 0 \\ -1 & 3 & 10 \\ 2 & 2 & 4 \end{bmatrix}$$

Row-reducing the matrix A yields,

$$\begin{bmatrix} \boxed{1} & 0 & -1 \\ 0 & \boxed{1} & 3 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

We see that $r = 2 \neq 3 = n$, where r is the number of nonzero rows and n is the number of columns. By Theorem LIVRN, the set S is linearly dependent.

2. Let S be the set of vectors below from \mathbb{C}^3 . (20 points)

$$S = \left\{ \begin{bmatrix} -1 \\ 2 \\ 1 \end{bmatrix}, \begin{bmatrix} 3 \\ 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 1 \\ 5 \\ 4 \end{bmatrix}, \begin{bmatrix} -6 \\ 5 \\ 1 \end{bmatrix} \right\}$$

- (a) Determine if the vector $\mathbf{y} = \begin{bmatrix} -5 \\ 3 \\ 0 \end{bmatrix}$ is an element of $\mathcal{S}p(S)$.

Solution: Form a linear combination, with unknown scalars, of S that equals \mathbf{y} ,

$$a_1 \begin{bmatrix} -1 \\ 2 \\ 1 \end{bmatrix} + a_2 \begin{bmatrix} 3 \\ 1 \\ 2 \end{bmatrix} + a_3 \begin{bmatrix} 1 \\ 5 \\ 4 \end{bmatrix} + a_4 \begin{bmatrix} -6 \\ 5 \\ 1 \end{bmatrix} = \begin{bmatrix} -5 \\ 3 \\ 0 \end{bmatrix}$$

We want to know if there are values for the scalars that make the vector equation true since that is the definition of membership in $\mathcal{S}p(S)$. By Theorem SLSLC any such values will also be solutions to the linear system represented by the augmented matrix,

$$\begin{bmatrix} -1 & 3 & 1 & -6 & -5 \\ 2 & 1 & 5 & 5 & 3 \\ 1 & 2 & 4 & 1 & 0 \end{bmatrix}$$

Row-reducing the matrix yields,

$$\begin{bmatrix} \boxed{1} & 0 & 2 & 3 & 2 \\ 0 & \boxed{1} & 1 & -1 & -1 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

From this we see that the system of equations is consistent (Theorem RCLS), and has a infinitely many solutions. Any solution will provide a linear combination of the vectors in R that equals \mathbf{y} . So $\mathbf{y} \in R$, for example,

$$(-10) \begin{bmatrix} -1 \\ 2 \\ 1 \end{bmatrix} + (-2) \begin{bmatrix} 3 \\ 1 \\ 2 \end{bmatrix} + (3) \begin{bmatrix} 1 \\ 5 \\ 4 \end{bmatrix} + (2) \begin{bmatrix} -6 \\ 5 \\ 1 \end{bmatrix} = \begin{bmatrix} -5 \\ 3 \\ 0 \end{bmatrix}$$

(b) Determine if the vector $\mathbf{w} = \begin{bmatrix} 2 \\ 1 \\ 3 \end{bmatrix}$ is an element of $\mathcal{Sp}(S)$.

Solution: Form a linear combination, with unknown scalars, of S that equals \mathbf{w} ,

$$a_1 \begin{bmatrix} -1 \\ 2 \\ 1 \end{bmatrix} + a_2 \begin{bmatrix} 3 \\ 1 \\ 2 \end{bmatrix} + a_3 \begin{bmatrix} 1 \\ 5 \\ 4 \end{bmatrix} + a_4 \begin{bmatrix} -6 \\ 5 \\ 1 \end{bmatrix} = \begin{bmatrix} 2 \\ 1 \\ 3 \end{bmatrix}$$

We want to know if there are values for the scalars that make the vector equation true since that is the definition of membership in $\mathcal{Sp}(S)$. By Theorem SLSLC any such values will also be solutions to the linear system represented by the augmented matrix,

$$\begin{bmatrix} -1 & 3 & 1 & -6 & 2 \\ 2 & 1 & 5 & 5 & 1 \\ 1 & 2 & 4 & 1 & 3 \end{bmatrix}$$

Row-reducing the matrix yields,

$$\begin{bmatrix} \boxed{1} & 0 & 2 & 3 & 0 \\ 0 & \boxed{1} & 1 & -1 & 0 \\ 0 & 0 & 0 & 0 & \boxed{1} \end{bmatrix}$$

With a leading 1 in the last column, the system is inconsistent (Theorem RCLS), so there are no scalars a_1, a_2, a_3, a_4 that will create a linear combination of the vectors in S that equal \mathbf{w} . So $\mathbf{w} \notin \mathcal{Sp}(S)$.

3. For the matrix A below, find a linearly independent set S so that the null space of T is spanned by S , that is, $\mathcal{N}(A) = \mathcal{S}p(S)$. (15 points)

$$A = \begin{bmatrix} -1 & -2 & 2 & 1 & 5 \\ 1 & 2 & 1 & 1 & 5 \\ 3 & 6 & 1 & 2 & 7 \\ 2 & 4 & 0 & 1 & 2 \end{bmatrix}$$

Solution: Theorem BNS provides formulas for $n - r$ vectors that will meet the requirements of this question. These vectors are the same ones listed in Theorem VFSLs when we solve the homogeneous system $\mathcal{L}\mathcal{S}(A, \mathbf{0})$, whose solution set is the null space (Definition NSM).

To apply Theorem BNS or Theorem VFSLs we first row-reduce the matrix, resulting in

$$B = \begin{bmatrix} \boxed{1} & 2 & 0 & 0 & 3 \\ 0 & 0 & \boxed{1} & 0 & 6 \\ 0 & 0 & 0 & \boxed{1} & -4 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

So we see that $n - r = 5 - 3 = 2$ and $F = \{2, 5\}$, so the vector form of a generic solution vector is

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} = x_2 \begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} + x_5 \begin{bmatrix} -3 \\ 0 \\ -6 \\ 4 \\ 1 \end{bmatrix}$$

So we have

$$\mathcal{N}(A) = \mathcal{S}p \left(\left\{ \begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} -3 \\ 0 \\ -6 \\ 4 \\ 1 \end{bmatrix} \right\} \right)$$

4. Given the set S below, find a linearly independent set T so that $\mathcal{S}p(T) = \mathcal{S}p(S)$. (15 points)

$$S = \left\{ \begin{bmatrix} 2 \\ -1 \\ 2 \end{bmatrix}, \begin{bmatrix} 3 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ -1 \end{bmatrix}, \begin{bmatrix} 5 \\ -1 \\ 3 \end{bmatrix} \right\}$$

Solution: Theorem RSS says we can make a matrix with these four vectors as columns, row-reduce, and just keep the columns with indices in the set D . Here we go, forming the relevant matrix and row-reducing,

$$\begin{bmatrix} 2 & 3 & 1 & 5 \\ -1 & 0 & 1 & -1 \\ 2 & 1 & -1 & 3 \end{bmatrix} \xrightarrow{\text{RREF}} \begin{bmatrix} \boxed{1} & 0 & -1 & 1 \\ 0 & \boxed{1} & 1 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

Analyzing the row-reduced version of this matrix, we see that the first two columns are pivot columns, so $D = \{1, 2\}$. Theorem RSS says we need only “keep” the first two columns to create a set with the requisite properties,

$$T = \left\{ \begin{bmatrix} 2 \\ -1 \\ 2 \end{bmatrix}, \begin{bmatrix} 3 \\ 0 \\ 1 \end{bmatrix} \right\}$$

5. Suppose that \mathbf{x} is a solution to $\mathcal{LS}(A, \mathbf{b})$ and that \mathbf{z} is a solution to the homogeneous system $\mathcal{LS}(A, \mathbf{0})$. Prove that $\mathbf{x} + \mathbf{z}$ is a solution to $\mathcal{LS}(A, \mathbf{b})$. (15 points)

Solution: Suppose that A has n columns, so $\mathbf{x}, \mathbf{z} \in \mathbb{C}^n$. Give the components of \mathbf{x} and \mathbf{z} names and apply Definition CVA,

$$\mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ \vdots \\ x_n \end{bmatrix} \quad \mathbf{z} = \begin{bmatrix} z_1 \\ z_2 \\ z_3 \\ \vdots \\ z_n \end{bmatrix} \quad \mathbf{x} + \mathbf{z} = \begin{bmatrix} x_1 + z_1 \\ x_2 + z_2 \\ x_3 + z_3 \\ \vdots \\ x_n + z_n \end{bmatrix}$$

We wish to prove that the latter vector is a solution to $\mathcal{LS}(A, \mathbf{b})$ on the assumption that \mathbf{x} and \mathbf{z} are solutions to the given systems. Suppose that a single equation from this system (the i -th one) has the form,

$$a_{i1}x_1 + a_{i2}x_2 + a_{i3}x_3 + \cdots + a_{in}x_n = b_i$$

Evaluate the left-hand side of this equation with the components of the proposed solution vector $\mathbf{x} + \mathbf{z}$,

$$\begin{aligned} & a_{i1}(x_1 + z_1) + a_{i2}(x_2 + z_2) + a_{i3}(x_3 + z_3) + \cdots + a_{in}(x_n + z_n) \\ &= a_{i1}x_1 + a_{i1}z_1 + a_{i2}x_2 + a_{i2}z_2 + a_{i3}x_3 + a_{i3}z_3 + \cdots + a_{in}x_n + a_{in}z_n && \text{Distributivity} \\ &= a_{i1}x_1 + a_{i2}x_2 + a_{i3}x_3 + \cdots + a_{in}x_n + a_{i1}z_1 + a_{i2}z_2 + a_{i3}z_3 + \cdots + a_{in}z_n && \text{Commutativity} \\ &= a_{i1}x_1 + a_{i2}x_2 + a_{i3}x_3 + \cdots + a_{in}x_n + 0 && \mathbf{z} \text{ solution to } \mathcal{LS}(A, \mathbf{0}) \\ &= b_i + 0 && \mathbf{x} \text{ solution to } \mathcal{LS}(A, \mathbf{b}) \\ &= b_i \end{aligned}$$

So equation i is true for all i , and we see that $\mathbf{x} + \mathbf{z}$ is a solution to $\mathcal{LS}(A, \mathbf{b})$.

6. Suppose that \mathbf{v}_1 and \mathbf{v}_2 are any two vectors from \mathbb{C}^m . Prove the following set equality. (15 points)

$$\mathcal{Sp}(\{\mathbf{v}_1, \mathbf{v}_2\}) = \mathcal{Sp}(\{\mathbf{v}_1 + \mathbf{v}_2, \mathbf{v}_1 - \mathbf{v}_2\})$$

Solution: This is an equality of sets, so Technique SE applies.

The “easy” half first. Show that $X = \mathcal{Sp}(\{\mathbf{v}_1 + \mathbf{v}_2, \mathbf{v}_1 - \mathbf{v}_2\}) \subseteq \mathcal{Sp}(\{\mathbf{v}_1, \mathbf{v}_2\}) = Y$.

Choose $\mathbf{x} \in X$. Then $\mathbf{x} = a_1(\mathbf{v}_1 + \mathbf{v}_2) + a_2(\mathbf{v}_1 - \mathbf{v}_2)$ for some scalars a_1 and a_2 . Then,

$$\begin{aligned} \mathbf{x} &= a_1(\mathbf{v}_1 + \mathbf{v}_2) + a_2(\mathbf{v}_1 - \mathbf{v}_2) \\ &= a_1\mathbf{v}_1 + a_1\mathbf{v}_2 + a_2\mathbf{v}_1 + (-a_2)\mathbf{v}_2 \\ &= (a_1 + a_2)\mathbf{v}_1 + (a_1 - a_2)\mathbf{v}_2 \end{aligned}$$

which qualifies \mathbf{x} for membership in Y , as it is a linear combination of $\mathbf{v}_1, \mathbf{v}_2$.

Now show the opposite inclusion, $Y = \mathcal{Sp}(\{\mathbf{v}_1, \mathbf{v}_2\}) \subseteq \mathcal{Sp}(\{\mathbf{v}_1 + \mathbf{v}_2, \mathbf{v}_1 - \mathbf{v}_2\}) = X$.

Choose $\mathbf{y} \in Y$. Then there are scalars b_1, b_2 such that $\mathbf{y} = b_1\mathbf{v}_1 + b_2\mathbf{v}_2$. Rearranging, we obtain,

$$\begin{aligned} \mathbf{y} &= b_1\mathbf{v}_1 + b_2\mathbf{v}_2 \\ &= \frac{b_1}{2} [(\mathbf{v}_1 + \mathbf{v}_2) + (\mathbf{v}_1 - \mathbf{v}_2)] + \frac{b_2}{2} [(\mathbf{v}_1 + \mathbf{v}_2) - (\mathbf{v}_1 - \mathbf{v}_2)] \\ &= \frac{b_1 + b_2}{2} (\mathbf{v}_1 + \mathbf{v}_2) + \frac{b_1 - b_2}{2} (\mathbf{v}_1 - \mathbf{v}_2) \end{aligned}$$

This is an expression for \mathbf{y} as a linear combination of $\mathbf{v}_1 + \mathbf{v}_2$ and $\mathbf{v}_1 - \mathbf{v}_2$, earning \mathbf{y} membership in X . Since X is a subset of Y , and vice versa, we see that $X = Y$, as desired.