

Show *all* of your work and *explain* your answers fully. There is a total of 100 possible points. If you use a calculator or Mathematica on a problem be sure to write down both the input and output.

1. In the vector space of 2×2 matrices, M_{22} , determine if the set

$$P = \left\{ \begin{bmatrix} 2 & 1 \\ -1 & 3 \end{bmatrix}, \begin{bmatrix} -3 & 0 \\ 2 & -2 \end{bmatrix}, \begin{bmatrix} -1 & 4 \\ 2 & 6 \end{bmatrix} \right\}$$

is linearly independent. (15 points)

Solution: Begin with a relation of linear dependence (Definition RLD) on P with three unknown scalars, and determine if they can must be trivial, or if there are non-trivial possibilities,

$$\begin{aligned} \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} &= a \begin{bmatrix} 2 & 1 \\ -1 & 3 \end{bmatrix} + b \begin{bmatrix} -3 & 0 \\ 2 & -2 \end{bmatrix} + c \begin{bmatrix} -1 & 4 \\ 2 & 6 \end{bmatrix} \\ &= \begin{bmatrix} 2a - 3b - c & a + 4c \\ -a + 2b + 2c & 3a - 2c + 6c \end{bmatrix} \end{aligned}$$

The definition of matrix equality (Definition ME) provides a homogeneous system of 4 linear equation in 3 variables,

$$\begin{aligned} 2a - 3b - c &= 0 \\ a + 4c &= 0 \\ -a + 2b + 2c &= 0 \\ 3a - 2c + 6c &= 0 \end{aligned}$$

Solving this system leads to non-trivial solutions (such as $a = -4$, $b = -3$, $c = 1$) which provide non-trivial relations of linear dependence on P , so by Definition LI, the set P is linearly dependent.

2. In the vector space of polynomials of degree at most 2, P_2 , does the set

$$Q = \{1 + 3x - x^2, 2 + x + 3x^2, -1 + 4x^2\}$$

span P_2 ? (15 points)

Solution: Can we write an arbitrary polynomial in P_2 , say $a + bx + cx^2$ as a linear combination of the elements of Q ? Equivalently, can we find scalars, a_1, a_2, a_3 so that

$$\begin{aligned} a + bx + cx^2 &= a_1(1 + 3x - x^2) + a_2(2 + x + 3x^2) + a_3(-1 + 4x^2) \\ &= (a_1 + 2a_2 - a_3) + (3a_1 + a_2)x + (-a_1 + 3a_2 + 4a_3)x^2 \end{aligned}$$

Equating coefficients, according to the definition of equality in P_2 , we arrive at a system of three equations in the three variables a_1, a_2, a_3 , $\mathcal{LS}(A, \mathbf{b})$, where

$$A = \begin{bmatrix} 1 & 2 & -1 \\ 3 & 1 & 0 \\ -1 & 3 & 4 \end{bmatrix} \qquad \mathbf{b} = \begin{bmatrix} a \\ b \\ c \end{bmatrix}$$

Since A row-reduces to the identity matrix I_3 , by Theorem NMRRI, A is nonsingular, and Theorem NMUS tells us this system always has a (unique) solution. So we can always find the scalars a_1, a_2, a_3 and so $\langle Q \rangle = P_2$ and by Definition TSVS, Q spans P_2 . (Another approach is to establish the linear independence of Q and then the known dimension of P_2 allows us to apply Theorem G to establish the spanning property.)

3. In the vector space of polynomials with degree at most 2, P_2 , the set

$$X = \{a + bx + cx^2 \mid a - 2b + 5c = 0\}$$

is a subspace of P_2 . (You may assume these statements so far and **do not** need to prove them.) Find the dimension of X (with proof). (15 points)

Solution: We must find a basis of X in order to determine the dimension. We first will try to find a spanning set and hope for its linear independence,

$$\begin{aligned} X &= \{a + bx + cx^2 \mid a - 2b + 5c = 0\} \\ &= \{a + bx + cx^2 \mid a = 2b - 5c\} \\ &= \{(2b - 5c) + bx + cx^2 \mid b, c \in \mathbb{C}\} \\ &= \{(2b + bx) + (-5c + cx^2) \mid b, c \in \mathbb{C}\} \\ &= \{b(2 + x) + c(-5 + x^2) \mid b, c \in \mathbb{C}\} \\ &= \langle \{2 + x, -5 + x^2\} \rangle \end{aligned}$$

So $P = \{2 + x, -5 + x^2\}$ is a spanning set for X (Definition TSVS). Is P linearly independent? Begin with a relation of linear dependence (Definition RLD),

$$\begin{aligned} 0 + 0x + 0x^2 &= a_1(2 + x) + a_2(-5 + x^2) \\ &= (2a_1 - 5a_2) + a_1x + a_2x^2 \end{aligned}$$

Equality of polynomials (Example VSP) implies that $a_1 = a_2 = 0$, so by Definition LI, P is linearly independent. Definition B says that P is a basis of X , and finally, Definition D, tells us that X has dimension 2.

4. In the vector space of 2×2 matrices, M_{22} , the set

$$W = \left\{ \begin{bmatrix} a & b \\ c & d \end{bmatrix} \mid a - 3b + c - 4d = 0 \right\}$$

is a subspace with dimension 3. (You may assume these statements so far and **do not** need to prove them.) For each set of 2×2 matrices below, determine if they have the indicated properties. (25 points)

(a) Does R span W ? $R = \left\{ \begin{bmatrix} 6 & 1 \\ 1 & 1 \end{bmatrix}, \begin{bmatrix} 2 & 3 \\ -1 & -2 \end{bmatrix} \right\}$

Solution: Since the size of R is less than the dimension of W , Theorem G tells us that R does not span W .

(b) Is T a basis of W ? $T = \left\{ \begin{bmatrix} 3 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} -1 & 0 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 4 & 0 \\ 0 & 1 \end{bmatrix} \right\}$

Solution: Any basis of W must have size 3 (Theorem BIS), so T cannot be ruled out as a basis based on size alone. We first check linear independence of T with a relation of linear dependence (Definition RLD),

$$\begin{aligned} \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} &= a_1 \begin{bmatrix} 3 & 1 \\ 0 & 0 \end{bmatrix} + a_2 \begin{bmatrix} -1 & 0 \\ 1 & 0 \end{bmatrix} + a_3 \begin{bmatrix} 4 & 0 \\ 0 & 1 \end{bmatrix} \\ &= \begin{bmatrix} 3a_1 - a_2 + 4a_3 & a_1 \\ a_2 & a_3 \end{bmatrix} \end{aligned}$$

Applying the definition of matrix equality (Definition ME), we conclude that $a_1 = a_2 = a_3 = 0$. So by Definition LI, T is linearly independent. Then, along with the size of T equaling the dimension of W , Theorem G tells us that T spans W . Finally, Definition B is fulfilled and T is a basis of W .

(c) Does S span W ? $S = \left\{ \begin{bmatrix} 0 & 2 \\ 2 & -1 \end{bmatrix}, \begin{bmatrix} 8 & 15 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 3 & 1 \\ 4 & 1 \end{bmatrix} \right\}$

Solution: The matrix $\begin{bmatrix} 8 & 15 \\ 0 & 0 \end{bmatrix}$ is not an element of W , so the span of S , $\langle S \rangle$ will contain elements of M_{22} that are not in W . Thus, S does not span W .

5. Suppose that $S = \{\mathbf{v}_1, \mathbf{v}_2\}$ is a linearly independent set in the vector space V . Prove that $T = \{4\mathbf{v}_1 + \mathbf{v}_2, 5\mathbf{v}_1 + \mathbf{v}_2\}$ is a linearly independent set in V . (15 points)

Solution: Begin with a relation of linear dependence on T with the aim of determining that the two unknown scalars *must* both be zero.

$$\begin{aligned} \mathbf{0} &= a_1(4\mathbf{v}_1 + \mathbf{v}_2) + a_2(5\mathbf{v}_1 + \mathbf{v}_2) && \text{Definition RLD} \\ &= 4a_1\mathbf{v}_1 + a_1\mathbf{v}_2 + 5a_2\mathbf{v}_1 + a_2\mathbf{v}_2 && \text{Property DVA} \\ &= 4a_1\mathbf{v}_1 + 5a_2\mathbf{v}_1 + a_1\mathbf{v}_2 + a_2\mathbf{v}_2 && \text{Property AC} \\ &= (4a_1 + 5a_2)\mathbf{v}_1 + (a_1 + a_2)\mathbf{v}_2 && \text{Property DSA} \end{aligned}$$

We now have a relation of linear dependence on S (Definition RLD), which is a set of vectors assumed to be linearly independent, so by Definition LI we conclude that the two scalars in the linear combination are both zero,

$$\begin{aligned} 4a_1 + 5a_2 &= 0 \\ a_1 + a_2 &= 0 \end{aligned}$$

This is a homogeneous system with a nonsingular coefficient matrix (check this!), so by Theorem NMUS, the solution is unique and must be the trivial solution $a_1 = 0, a_2 = 0$. By Definition LI we conclude that T is linearly independent.

6. Suppose that \mathbf{v} is an element of the vector space V , and $\alpha \in \mathbb{C}$. then Theorem AISM tells us that $(-1)\mathbf{v} = -\mathbf{v}$. Prove the more general statement that $(-\alpha)\mathbf{v} = -(\alpha\mathbf{v})$. (15 points)

Solution:

$$\begin{aligned} (-\alpha)\mathbf{v} &= ((-1)\alpha)\mathbf{v} && \text{Arithmetic in } \mathbb{C} \\ &= (-1)(\alpha\mathbf{v}) && \text{Property SMA} \\ &= -(\alpha\mathbf{v}) && \text{Theorem AISM} \end{aligned}$$