

Show *all* of your work and *explain* your answers fully. There is a total of 100 possible points. If you use a calculator or Mathematica on a problem be sure to write down both the input and output.

1. Find all solutions to the system of equations below, writing the solutions as a set employing the vector form of a solution. (10 points)

$$\begin{aligned} -2x_1 - 6x_2 + x_3 + 4x_4 + 9x_5 &= 7 \\ 3x_1 + 9x_2 + 5x_3 + 7x_4 - 7x_5 &= 9 \end{aligned}$$

Solution: Theorem VFSLs references the row-reduced version of the augmented matrix of the system. So we form the augmented matrix and find a row-equivalent matrix in reduced row-echelon form,

$$\left[\begin{array}{cccccc|ccc} -2 & -6 & 1 & 4 & 9 & 7 & 1 & 3 & 0 & -1 & -4 & -2 \\ 3 & 9 & 5 & 7 & -7 & 9 & 0 & 0 & 1 & 2 & 1 & 3 \end{array} \right] \xrightarrow{\text{RREF}}$$

The non-pivot columns have indices $F = \{2, 4, 5\}$. Based on this alone, we know a typical solution vector looks like

$$\mathbf{x} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} + x_2 \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} 0 \\ 1 \\ 1 \\ 0 \end{bmatrix} + x_5 \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix}$$

Applying the theorem, or unraveling the equations represented by each row of the augmented matrix, we can use the vector form of a solution vector in a set construction to achieve the solution set,

$$\left\{ \begin{bmatrix} -2 \\ 0 \\ 3 \\ 0 \\ 0 \end{bmatrix} + x_2 \begin{bmatrix} -3 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} 1 \\ 0 \\ -2 \\ 1 \\ 0 \end{bmatrix} + x_5 \begin{bmatrix} 4 \\ 0 \\ -1 \\ 0 \\ 1 \end{bmatrix} \mid x_2, x_4, x_5 \in \mathbb{C} \right\}$$

2. For the matrix A below, find a linearly independent set P such that $\langle P \rangle = \mathcal{N}(A)$, i.e. the span of P equals the null space of A . (15 points)

$$A = \begin{bmatrix} -2 & -4 & -4 & 10 & -4 \\ -4 & -1 & 5 & 1 & 24 \\ 2 & -1 & -4 & 1 & -15 \end{bmatrix}$$

Solution: Theorem BNS provides the necessary vectors. First, we need to row-reduce the matrix to find a row-equivalent matrix in reduced row-echelon form,

$$\left[\begin{array}{ccccc|ccccc} -2 & -4 & -4 & 10 & -4 & 1 & 0 & 0 & -3 & -2 \\ -4 & -1 & 5 & 1 & 24 & 0 & 1 & 0 & 1 & -1 \\ 2 & -1 & -4 & 1 & -15 & 0 & 0 & 1 & -2 & 3 \end{array} \right] \xrightarrow{\text{RREF}}$$

The non-pivot columns have indices $F = \{4, 5\}$, and with an application of Theorem BNS, or consideration of solutions to the homogeneous system, $\mathcal{LS}(A, \mathbf{0})$, we find the linear independent set

$$P = \left\{ \begin{bmatrix} 3 \\ -1 \\ 2 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 2 \\ 1 \\ -3 \\ 0 \\ 1 \end{bmatrix} \right\}$$

whose span will be the null space of A .

3. Given the set S below, find a linearly independent set T such that $\langle T \rangle = \langle S \rangle$. (15 points)

$$S = \left\{ \begin{bmatrix} 1 \\ -2 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -2 \\ 5 \\ -4 \\ 1 \end{bmatrix}, \begin{bmatrix} -4 \\ 11 \\ -10 \\ 3 \end{bmatrix}, \begin{bmatrix} 1 \\ -4 \\ 6 \\ -3 \end{bmatrix}, \begin{bmatrix} -1 \\ 7 \\ -13 \\ 7 \end{bmatrix} \right\}$$

Solution: Theorem BS provides the tools for locating such a set. Let C be the matrix whose columns are the vectors in S , and then row-reduce,

$$C = \begin{bmatrix} 1 & -2 & -4 & 1 & -1 \\ -2 & 5 & 11 & -4 & 7 \\ 1 & -4 & -10 & 6 & -13 \\ 0 & 1 & 3 & -3 & 7 \end{bmatrix} \xrightarrow{\text{RREF}} \begin{bmatrix} \boxed{1} & 0 & 2 & 0 & 3 \\ 0 & \boxed{1} & 3 & 0 & 1 \\ 0 & 0 & 0 & \boxed{1} & -2 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

The pivot columns are $D = \{1, 2, 4\}$ so we can form the set T as simply the first three vectors of S , and know from Theorem BS that T is linearly independent and $\langle T \rangle = \langle S \rangle$,

$$T = \left\{ \begin{bmatrix} 1 \\ -2 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -2 \\ 5 \\ -4 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ -4 \\ 6 \\ -3 \end{bmatrix} \right\}$$

4. For each set below, determine if the set is linearly independent or linearly dependent. (15 points)

(a) $T = \left\{ \begin{bmatrix} 5 \\ 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} -2 \\ 3 \\ 5 \\ 1 \end{bmatrix}, \begin{bmatrix} -1 \\ 4 \\ 7 \\ 2 \end{bmatrix}, \begin{bmatrix} 6 \\ -2 \\ 2 \\ -2 \end{bmatrix} \right\}$

Solution: With 4 vectors from \mathbb{C}^4 we can make these vectors the columns of a matrix, B , and row-reduce the result,

$$B = \begin{bmatrix} 5 & -2 & -1 & 6 \\ 1 & 3 & 4 & -2 \\ 1 & 5 & 7 & 2 \\ 1 & 1 & 2 & -2 \end{bmatrix} \xrightarrow{\text{RREF}} \begin{bmatrix} \boxed{1} & 0 & 0 & 0 \\ 0 & \boxed{1} & 0 & 0 \\ 0 & 0 & \boxed{1} & 0 \\ 0 & 0 & 0 & \boxed{1} \end{bmatrix}$$

Since the row-reduced version of B is the 4×4 identity matrix, I_4 (Definition IM), we know by Theorem NMRI that the columns of B are linearly independent. Thus T is a linearly independent set.

(b) $R = \left\{ \begin{bmatrix} -2 \\ -1 \\ 4 \end{bmatrix}, \begin{bmatrix} 0 \\ 4 \\ 5 \end{bmatrix}, \begin{bmatrix} 2 \\ -2 \\ 8 \end{bmatrix}, \begin{bmatrix} 7 \\ 5 \\ 7 \end{bmatrix}, \begin{bmatrix} -2 \\ 6 \\ 1 \end{bmatrix} \right\}$

Solution: This is a set of $n = 5$ vectors from \mathbb{C}^3 and $n = 5 > 3 = m$, so by Theorem MVSLD the set R is linearly dependent.

5. Suppose that $\alpha \in \mathbb{C}$ is a scalar and $\mathbf{x} \in \mathbb{C}^m$ is a vector. Prove that $\overline{\alpha\mathbf{x}} = \overline{\alpha}\overline{\mathbf{x}}$ with a careful proof that uses the definition of vector equality (Definition CVE). (15 points)

Solution: For $1 \leq i \leq m$,

$$\begin{aligned} [\overline{\alpha\mathbf{x}}]_i &= \overline{[\alpha\mathbf{x}]_i} && \text{Definition CCCV} \\ &= \overline{\alpha [\mathbf{x}]_i} && \text{Definition CVSM} \\ &= \overline{\alpha} \overline{[\mathbf{x}]_i} && \text{Definition CCRM} \\ &= \overline{\alpha} [\overline{\mathbf{x}}]_i && \text{Definition CCCV} \end{aligned}$$

Then by Definition CVE we have $\overline{\alpha\mathbf{x}} = \overline{\alpha}\overline{\mathbf{x}}$.

6. Suppose that $\mathbf{u}, \mathbf{v} \in \mathbb{C}^m$ are two vectors. Use the definition of linear independence to prove that $S = \{\mathbf{u}, \mathbf{v}\}$ is a linearly dependent set if and only if one of the two vectors is a scalar multiple of the other. In other words, do not simply apply Theorem DLDS, the theorem that says linear dependence is equivalent to one vector being a linear combination of the others. (15 points)

Solution: (\Rightarrow) If S is linearly dependent, then there are scalars α and β , not both zero, such that $\alpha\mathbf{u} + \beta\mathbf{v} = \mathbf{0}$. Suppose that $\alpha \neq 0$, the proof proceeds similarly if $\beta \neq 0$. Now,

$$\begin{aligned} \mathbf{u} &= 1\mathbf{u} && \text{Property OC} \\ &= \left(\frac{1}{\alpha}\alpha\right)\mathbf{u} && \text{Property MICN} \\ &= \frac{1}{\alpha}(\alpha\mathbf{u}) && \text{Property SMAC} \\ &= \frac{1}{\alpha}(\alpha\mathbf{u} + \mathbf{0}) && \text{Property ZC} \\ &= \frac{1}{\alpha}(\alpha\mathbf{u} + \beta\mathbf{v} - \beta\mathbf{v}) && \text{Property AIC} \\ &= \frac{1}{\alpha}(\mathbf{0} - \beta\mathbf{v}) && \text{Definition LICV} \\ &= \frac{1}{\alpha}(-\beta\mathbf{v}) && \text{Property ZC} \\ &= \frac{-\beta}{\alpha}\mathbf{v} && \text{Property SMAC} \end{aligned}$$

which shows that \mathbf{u} is a scalar multiple of \mathbf{v} .

(\Leftarrow) Suppose now that \mathbf{u} is a scalar multiple of \mathbf{v} . More precisely, suppose there is a scalar γ such that $\mathbf{u} = \gamma\mathbf{v}$. Then

$$\begin{aligned} (-1)\mathbf{u} + \gamma\mathbf{v} &= (-1)\mathbf{u} + \mathbf{u} \\ &= (-1)\mathbf{u} + (1)\mathbf{u} && \text{Property OC} \\ &= ((-1) + 1)\mathbf{u} && \text{Property DSAC} \\ &= \mathbf{0}\mathbf{u} && \text{Property AICN} \\ &= \mathbf{0} && \text{Definition CVSM} \end{aligned}$$

This is a relation of linear dependence on S (Definition RLDCV), which is nontrivial since one of the scalars is -1 . Therefore S is linearly dependent by Definition LICV.