

2. Consider the linear transformation S below, which is invertible (you may assume this). Find a formula for the outputs of the inverse linear transformation S^{-1} . P_1 is the vector space of polynomials with degree at most 1. (25 points)

$$S: P_1 \rightarrow \mathbb{C}^2, \quad S(a+bx) = \begin{bmatrix} 2a+5b \\ a+3b \end{bmatrix}$$

Compute pre-images of a basis for the codomain: $\left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right\}$

$$S^{-1}\left(\begin{bmatrix} 1 \\ 0 \end{bmatrix}\right): \quad S(a+bx) = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \Rightarrow \begin{cases} 2a+5b=1 \\ a+3b=0 \end{cases} \Rightarrow \begin{cases} a=3 \\ b=-1 \end{cases}$$

$$S^{-1}\left(\begin{bmatrix} 1 \\ 0 \end{bmatrix}\right) = \{3-x\} \Rightarrow S^{-1}\left(\begin{bmatrix} 1 \\ 0 \end{bmatrix}\right) = 3-x$$

$$S^{-1}\left(\begin{bmatrix} 0 \\ 1 \end{bmatrix}\right): \quad S(a+bx) = \begin{bmatrix} 0 \\ 1 \end{bmatrix} \Rightarrow \begin{cases} 2a+5b=0 \\ a+3b=1 \end{cases} \Rightarrow \begin{cases} a=-5 \\ b=2 \end{cases}$$

$$S^{-1}\left(\begin{bmatrix} 0 \\ 1 \end{bmatrix}\right) = \{-5+2x\} \Rightarrow S^{-1}\left(\begin{bmatrix} 0 \\ 1 \end{bmatrix}\right) = -5+2x$$

Then,

$$\begin{aligned} S^{-1}\left(\begin{bmatrix} r \\ s \end{bmatrix}\right) &= S^{-1}\left(r\begin{bmatrix} 1 \\ 0 \end{bmatrix} + s\begin{bmatrix} 0 \\ 1 \end{bmatrix}\right) \\ &= rS^{-1}\left(\begin{bmatrix} 1 \\ 0 \end{bmatrix}\right) + sS^{-1}\left(\begin{bmatrix} 0 \\ 1 \end{bmatrix}\right) \\ &= r(3-x) + s(-5+2x) \\ &= (3r-5s) + (r+2s)x \end{aligned}$$

3. Prove that the function T below is a linear transformation. P_1 is the vector space of polynomials with degree at most 1. (15 points)

$$T: P_1 \rightarrow \mathbb{C}^2, \quad T(a+bx) = \begin{bmatrix} 3a-b \\ 4b \end{bmatrix}$$

$$\begin{aligned} \textcircled{1} \quad T((a_1 + b_1x) + (a_2 + b_2x)) &= T((a_1 + a_2) + (b_1 + b_2)x) \\ &= \begin{bmatrix} 3(a_1 + a_2) - (b_1 + b_2) \\ 4(b_1 + b_2) \end{bmatrix} = \begin{bmatrix} (3a_1 - b_1) + (3a_2 - b_2) \\ 4b_1 + 4b_2 \end{bmatrix} \\ &= \begin{bmatrix} 3a_1 - b_1 \\ 4b_1 \end{bmatrix} + \begin{bmatrix} 3a_2 - b_2 \\ 4b_2 \end{bmatrix} = T(a_1 + b_1x) + T(a_2 + b_2x) \end{aligned}$$

$$\begin{aligned} \textcircled{2} \quad T(\alpha(a+bx)) &= T(\alpha a + (\alpha b)x) = \begin{bmatrix} 3(\alpha a) - \alpha b \\ 4(\alpha b) \end{bmatrix} \\ &= \begin{bmatrix} \alpha(3a-b) \\ \alpha(4b) \end{bmatrix} = \alpha \begin{bmatrix} 3a-b \\ 4b \end{bmatrix} = \alpha T(a+bx) \end{aligned}$$

4. Suppose that $S: U \rightarrow V$ is an invertible linear transformation. Then prove that S^{-1} has one of the two defining properties of a linear transformation (either property, your choice, for full credit). (15 points)

Choose $\alpha \in \mathbb{C}$, $\underline{v} \in V$. Because S is invertible, S must be surjective (Theorem ILT15) so there exists a $\underline{u} \in U$ with $S(\underline{u}) = \underline{v}$ & equivalently, $S^{-1}(\underline{v}) = \underline{u}$.

$$\begin{aligned} \text{Then} \quad S^{-1}(\alpha \underline{v}) &= S^{-1}(\alpha S(\underline{u})) \\ &= S^{-1}(S(\alpha \underline{u})) \quad \underline{S} \text{ is a linear transformation} \\ &= \underline{I}_u(\alpha \underline{u}) \\ &= \alpha \underline{u} \\ &= \alpha S^{-1}(\underline{v}) \end{aligned}$$

which is the second defining property.